

AMENDMENTS TO THE CLAIMS:

This listing of claims will replace all prior versions and listings of claims in the application:

1. (Currently Amended) A system for automatically manipulating or annotating a second map when a first map is manipulated or annotated, the system comprising:
 - a map display;
 - a map processing platform in communication with the map display, wherein said map processing platform is adapted to:
 - receive a user annotation at a first location on a first map;
 - associate the user annotation with a set of first map coordinates using a georeferencing function of the first map;
 - associate the set of first map coordinates with a set of second map coordinates using a georeferencing function of the second map; and
 - ~~simultaneously~~ update [[a]] the second map with the user annotation at a location on the second map that corresponds to ~~said the~~ first location;
 - a storage platform coupled to the map processing platform; and
 - a user interaction device coupled to the map processing platform.

2. (Previously Presented) They system of claim 1, wherein the map display is enabled to display a first map in a first area of the map display and to display a second map in a second area of the map display.

3. (Original) The system of claim 1 wherein the map display is coupled to a graphics adapter.

4. (Original) The system of claim 1 wherein the processing platform is a microprocessor.

5. (Original) The system of claim 1 wherein the map processing platform is an application service provider.

6. (Original) The system of claim 1 wherein the map processing platform is located remotely from the map display.

7. (Previously Presented) The system of claim 1 wherein the storage platform comprises cached memory.

8. (Original) The system of claim 1 wherein the storage platform comprises system memory.

9. (Previously Presented) The system of claim 1 wherein the storage platform comprises random access memory.

10. (Original) The system of claim 1 wherein the user interaction device comprises a mouse.
11. (Original) The system of claim 1 wherein the map processing platform and the map display are coupled via a network.
12. (Original) The system of claim 1 wherein the network is the internet.
13. (Original) The system of claim 1 wherein the storage platform is associated with the map processing platform via a network.
14. (Original) The system of claim 13 wherein the network is the internet.
15. (Original) The system of claim 1 wherein the storage platform maintains code that enables the automatic manipulation of a second map when a first map is manipulated by:
 - determining a boundary of a geographic region of a first map;
 - converting the boundary of the geographic region of the first map into a corresponding boundary of a second map; and
 - configuring the boundary of the second map for display.

16. (Original) The system of claim 1 wherein the storage platform maintains code that enables the automatic manipulation of a second map when a first map is manipulated by:

- determining a boundary of a geographic region of a first map;
- converting the boundary of the geographic region of the first map into a corresponding boundary of a second map;
- configuring the boundary of the second map for display;
- receiving a selection of a first region of a first map; and
- receiving an interaction for multiple map manipulation by providing a user interaction with a map.

17. (Canceled)

18. (Currently Amended) A method of correlating a map annotation from a first map to a second map, the second map being geographically substantially similar to the first map comprising:

- detecting an annotation entry on the first map;
- associating the annotation entry with a set of first map coordinates using a georeferencing function of the first map;
- associating the set of ~~the~~ first map coordinates with a set of second map coordinates using a georeferencing function of the second map; and
- upon detecting the annotation entry, ~~simultaneously~~ enabling ~~the~~ display of the annotation entry on the second map.

19. (Original) The method of claim 18 wherein associating the set of first map coordinates locates the annotation entry within the second map such that the set of second map coordinates correspond geographically to the location of the annotation as defined by the set of first map coordinates.

20. (Currently Amended) A computer readable medium containing instructions executable by a computer to perform a method of correlating a map annotation between a first map and a second map, the second map being geographically substantially similar to the first map, the method comprising:

detecting an annotation entry on the first map;

associating the annotation entry with a set of first map coordinates using a georeferencing function of the first map;

associating the set of ~~[[the]]~~ first map coordinates with a set of second map coordinates using a georeferencing function of the second map; and

upon detecting the annotation entry, ~~simultaneously~~ enabling ~~[[the]]~~ display of the annotation entry on the second map.

21. (Previously Presented) The system for automatically manipulating or annotating a second map of claim 1, wherein the map processing platform is adapted to:

receive a user manipulation of a first map; and

implement the user manipulation on a second map.

22. (New) A method for synchronizing map images, the method comprising:

- displaying a first map on a display;
- displaying a second map on the display, wherein the second map shares at least a portion of a common geographic area with the first map;
- selecting boundaries to define a geographic region on the first map; and
- adjusting boundaries of the second map to display the defined geographic region.

23. (New) A method for automatically annotating a map, the method comprising:

- receiving an annotation on a first map;
- determining a location of the annotation on the first map using a coordinate system of the first map;
- converting the location to longitude and latitude using a georeferencing function of the first map;
- determining a corresponding location on the second map based on the longitude and latitude using a georeferencing function of the second map; and
- displaying a second annotation on the second map at the corresponding location.